THE MDL PRINCIPLE FOR ARBITRARY DATA:  
EITHER DISCRETE OR CONTINUOUS OR NONE OF THEM  

Joe Suzuki  

Department of Mathematics, Graduate School of Science, Osaka University,  
1-1 Machikaneyama-cho Toyonaka, Osaka 560-0043, Japan  

ABSTRACT  

Consider universal data compression: the length $l(x^n)$ of sequence $x^n \in A^n$ with finite alphabet $A$ and length $n$ satisfies Kraft’s inequality over $A^n$, and $\frac{1}{n} \log P^n(x^n)$ almost surely converges to zero as $n$ grows for the $Q^n(x^n) = 2^n f(x^n)$ and any stationary ergodic source $P$. In this paper, we say such a $Q$ is a universal Bayesian measure. We generalize the notion to the sources which the random variables may be either discrete, continuous, or none of them. The previous work by Ryabko was applied only to the case that a density function exists, and an additional constraint on $P$ was required. The universal Bayesian measure constructed in this paper has many applications to infer relation among random variables, and extends the application area of the minimum description length principle.

1. SUMMARY

Suppose we wish to know if discrete random variables $X, Y$ are independent ($X \perp Y$) given $n$ pairs of examples $\{(x_i, y_i)\}_{i=1}^n$ emitted by $(X, Y)$. If the probabilities of $x^n = (x_1, \cdots, x_n)$, $y^n = (y_1, \cdots, y_n)$, and $(x^n, y^n)$ are expressed by $P^n_X(x^n|\theta_X)$, $P^n_Y(y^n|\theta_Y)$, and $P^n_{XY}(x^n, y^n|\theta_{XY})$, respectively, using unknown parameters $\theta_X, \theta_Y, \theta_{XY}$, one way to deal with this problem is to decide $X \not\perp Y$ if and only if

$$pQ^n_X(x^n)Q^n_Y(y^n) \geq (1-p)Q^n_{XY}(x^n, y^n),$$

where $p$ is the prior probability of $X \not\perp Y$, and the three values are defined by

$$Q^n_X(x^n) := \int P^n(x^n|\theta_X)w_X(\theta_X)d\theta_X,$$

$$Q^n_Y(y^n) := \int P^n(y^n|\theta_Y)w_Y(\theta_Y)d\theta_Y,$$

$$Q^n_{XY}(x^n, y^n) := \int P^n(x^n, y^n|\theta_{XY})w_{XY}(\theta_{XY})d\theta_{XY} \quad (1)$$

using weights $w_X, w_Y, w_{XY}$ over the parameters $\theta_X, \theta_Y, \theta_{XY}$, respectively.

To this end, let $A$ be the finite set in which $X$ takes values. There are many options of $Q_X$ such that

$$\sum_{x^n \in A^n} Q^n_X(x^n) \leq 1. \quad (2)$$

For example$^1$, $Q^n_X(x^n) = |A|^{-n}$ for $x^n \in A^n$ satisfies the condition. However, such a $Q_X$ cannot be an alternative of $P$ for large $n$ because $Q^n_X$ does not converges to $P^n$ in any sense. On the other hand, if we choose $w_X(\theta_X) \propto \prod_{x \in A} \theta^{-a[x]}$ with constants $(a[x] = \frac{1}{2})_{x \in A}$ (Krichevsky-Trofimov [3]), then the quantity $-\frac{1}{n} \log Q^n_X(x^n)$ almost surely converges to its entropy $H(\theta_X)$ for any independent and identically distributed (i.i.d) source $P^n(x^n|\theta_X) = \prod_{x \in A} \theta^{-c[x]}$ with parameters $\theta = (\theta_x)_{x \in A}$ and frequencies $(c[x])_{x \in A}$ in $x^n \in A^n$ [6]. Furthermore, the Shannon-McMillian-Breiman theorem [2] states that

$$-\frac{1}{n} \log P^n(x^n|\theta_X) \rightarrow H(\theta_X)$$

almost surely for any stationary ergodic source $\theta_X$, so that almost surely

$$\frac{1}{n} \log \frac{P^n_X(x^n)}{Q^n_X(x^n)} \rightarrow 0 \quad (3)$$

if we write $P^n(x^n|\theta_X)$ by $P^n_X(x^n)$. In this paper, we say such a $Q_X$ satisfying (2)(3) to be a universal Bayesian measure associated with finite set $A$. From the above discussion, we can say that a universal Bayesian measure exists for finite sources.

However, what if $X, Y$ are arbitrary without assuming they are discrete? Recently, for random variable $X$ such that its density function $f_X$ exists, Boris Ryabko [5] proved that there exists $g_X$ such that

$$\int_{x \in \mathbb{R}^n} g^n_X(x^n) \leq 1$$

and

$$\frac{1}{n} \log \frac{f^n_X(x^n)}{g^n_X(x^n)} \rightarrow 0 \quad (4)$$

for any $f_X$ satisfying a condition. The estimation is based on a specific sequence of histograms: let $A_0 = \{A\}$, and $A_{j+1}$ is a refinement of $A_j$, where $A$ is the range of $X$: for each $j = 1, 2, \cdots$, we estimate the density function $f^n_X(x^n)$ based on each histogram $A_j$; and if we obtain $g^n_X(x^n)$ as the estimation for $j = 1, 2, \cdots$, then we obtain the final estimation $g^n(x^n) = \sum_j w_j g^n_j(x^n)$, where $w_j > 0$ and $\sum_j w_j = 1$. But the estimation depends on the specific $\{A_j\}$ and requires $D(f_X||f_j) \rightarrow 0$.

$^1|A|$ denotes the cardinality of set $A$. 


as \( j \to \infty \). Therefore, sufficient prior information is required.

In addition, in order to decide whether \( X \perp Y \) or not is made, we need to construct Bayesian measures \( Q_{XY} \) and \( g_{XY} \) for two variables \( X, Y \) extending \( Q_X \) and \( g_X \) for one variable \( X \).

We admire Ryabko’s original work [5], and admit that the basic idea was already there. However, we need to seek further generalizations for practical development of the theory. In this paper, we

1. remove the constraint that \( X \) should be either discrete or continuous to obtain a general form of universality containing (3)(4) as special cases;
2. remove the condition that Ryabko [5] posed; and
3. construct universal measures for more than one variables,

so that we establish that a universal Bayesian measure unconditionally exists for any stationary ergodic random variable which may be either discrete, continuous, or none of them. Once we can deal with universal Bayesian measures for more than one random variables, we can infer relation among them from given examples.

For simplicity, in this paper, we assume that the underlying source is i.i.d. although the discussion will hold for stationary ergodic sources.

Let us state the main results without proof. Let \( B \) be the entire Borel sets of \( \mathbb{R} \). Let \( \mu_X(D) := P(X \in D) \) for \( D \in B \), and \( \eta_X \) a \( \sigma \)-finite measure, i.e. there exists \( \{A_j\} \) such that \( A_j \in \mathcal{F}, \cup_j A_j = \Omega \) and \( \eta_X(A_i) < \infty \) for measure space \( (\Omega, \mathcal{F}) \), and we assume\(^{\dagger} \) \( \mu_X \ll \eta_X \), i.e., 

\[ \eta_X(D) = 0 \implies \mu_X(D) = 0 \text{ for any } D \in B. \]

**Theorem 1** There exists a \( \nu_X^n \ll \eta_X^n \) such that \( \nu_X^n(A^n) \leq 1 \) and with probability one as \( n \to \infty \)

\[ \frac{1}{n} \log \frac{d\nu_X^n}{d\eta_X^n}(x^n) \to 0 \quad (5) \]

We notice that the Radon-Nikodym derivative is expressed by the ratio

\[ \frac{d\nu_X^n}{d\eta_X^n}(x^n) = \frac{d\mu_X^n}{d\eta_X^n}(x^n) \frac{d\eta_X^n}{d\mu_X^n}(x^n) \]

and that the density function \( \frac{d\nu_X^n}{d\eta_X^n}(x^n) \) in the generalized sense is estimated by constructing the quantity \( \frac{d\nu_X^n}{d\eta_X^n}(x^n) \).

If \( \eta_X \) is the Lebesgue measure of \( \mathbb{R} \), then the result reduces to Ryabko’s result \( f_X = \frac{d\mu_X^n}{d\eta_X^n}(x^n) \) and \( g_X = \frac{d\nu_X^n}{d\eta_X^n}(x^n) \). However, we have successfully removed the condition \( D \{f_X \parallel f_Y\} \to 0 \) as \( j \to \infty \).

In a similar way, let \( \mu_Y(D) := P(Y \in D) \) for \( D \in B \), and \( \eta_Y \) a \( \sigma \)-finite measure, and we assume \( \mu_Y \ll \eta_Y \). Furthermore, let \( \mu_{XY}(D \times D') := P(X \in D, Y \in D') \)

\( \frac{d\mu_{XY}^n}{d\eta_{XY}^n}(x^n, y^n) \to 0 \)

Let \( D, D' \in B \), and \( \eta_{XY} \) the product measure of \( \eta_X, \eta_Y \).

Let \( B \) be the range of \( Y \).

**Theorem 2** There exists a \( \nu_{XY}^n \ll \eta_{XY}^n \) such that \( \nu_{XY}^n(A^n \times B^n) \leq 1 \) and with probability one as \( n \to \infty \)

\[ \frac{1}{n} \log \frac{d\nu_{XY}^n}{d\eta_{XY}^n}(x^n, y^n) \to 0 \quad (6) \]

The results in this paper are rather theoretical but contain many applications such as

1. Bayesian network structure learning [7, 8],
2. a variant of the Chow-Liu algorithm learning a forest given examples [7, 9].

In fact, in any database, both discrete and continuous fields are present. Then, we need to find dependency among those attributes. However, the existing results only deal with either only discrete data or only continuous data. This paper deals with the most general and realistic cases.

For contributions to statistics, constructing such a universal Bayesian measure means establishing a general form of Bayesian Information Criteria (BIC). Suppose we have a countable number of models \( m = 1, 2, \ldots \) each of which expresses a relation among random variables. If we construct a universal Bayesian measure \( q(x^n|m) \) w.r.t. model \( m \) given data \( x^n \), then we can select \( m \) such that \( -\log p(m) - \log q(x^n|m) \) is minimized, where \( p(m) \) is the prior probability of model \( m \). In fact, the measure applies to all the cases that BIC/MDL applied thus far.

**2. REFERENCES**